

# Data and Models

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RWTH Aachen

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# Outline

## 1 Introduction

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## 2 3 Scenarios

- Electron Microscopy
- EELS Electron Energy Loss Spectroscopy
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- Nonparametric Estimation - A Sample Result

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## 4 Data-Assimilation - "Small Data" Problem

# What is it all about...

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## Conceptual ingredients:

- adaptivity
- nonlinear recovery
- embedding into a proper continuous framework to exploit natural “problem metrics”



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...has led to “unexpected” algorithmic structures...

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# Precision in STEM Imaging

scanning transmission electron microscopy

Collaborators: B. Berkels, N. Mevenkamp (AICES),  
Ernst-Ruska-Center Jülich, P. Voyles (University of Wisconsin), P.  
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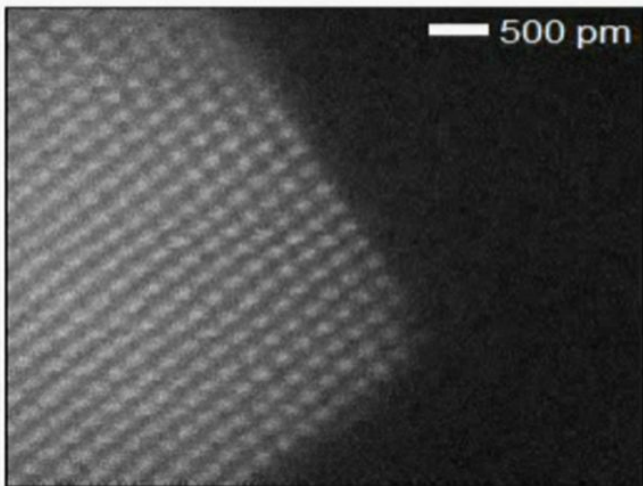
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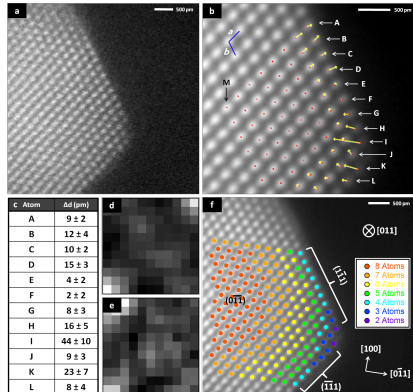
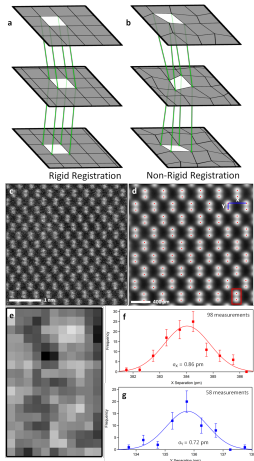
## Obstructions:

- high electron dose destroys specimen
- low electron dose causes low signal-to-noise ratio
- Poisson noise
- multiscale locally distorted movement of specimen

# Pt nanocatalyst

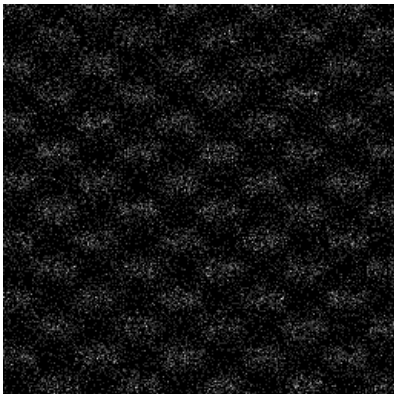


# Results - sub-picometer precision

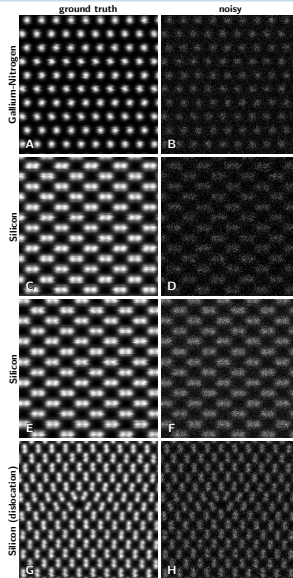


Result: improve precision by factors 5 to 10

## ...before and after...Perfect Silicon



## ...before and after... Perfect Silicon Gallium Nitride



# Methods

## Key ingredients:

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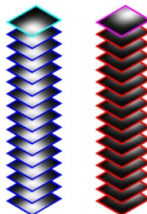
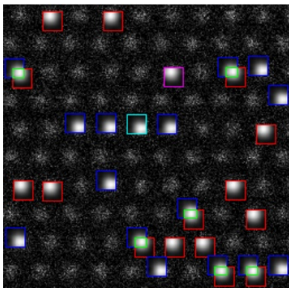
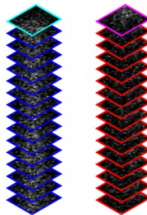
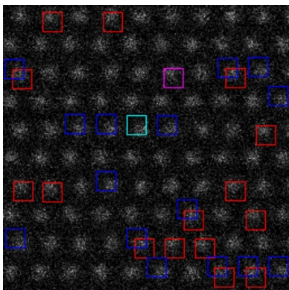
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A. B. Yankovich, B. Berkels, W. Dahmen, P. Binev, S.I. Sanchez, S.A. Bradley, and P.M. Voyles, Picometer precision STEM imaging of Pt Nanocatalysts, Nature Communications 5, Article number: 4155 (2014) doi:10.1038/ncomms5155

N. Mevenkamp, P. Binev, W. Dahmen, P.M. Voyles, A.B. Yankovich, and B. Berkels, Poisson noise removal from high-resolution STEM images based on periodic block matching, Advanced Structural and Chemical Imaging, DOI 10.1186/s40679-015-0004-8



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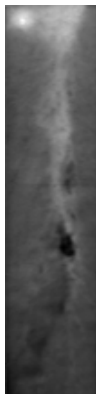
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# EELS-Images

electron energy loss spectroscopy  $\rightsquigarrow$  “function valued pixels”

**Collaborations:** B. Berkels (AICES), M. Duchamps (FZ Jülich),  
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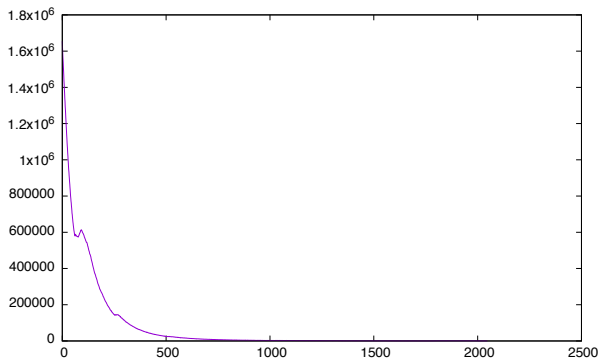


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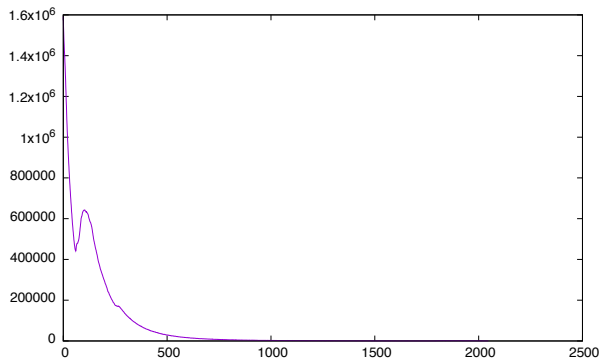


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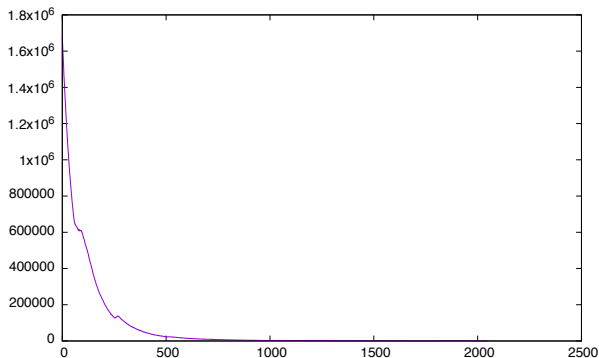


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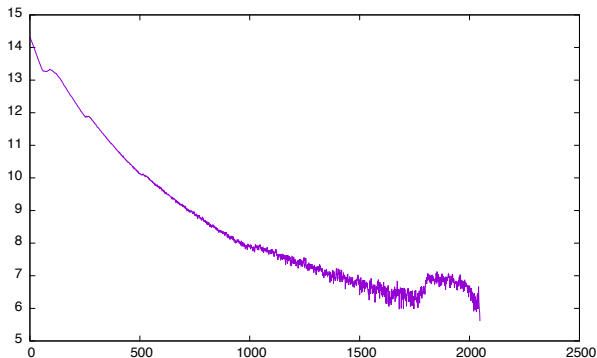


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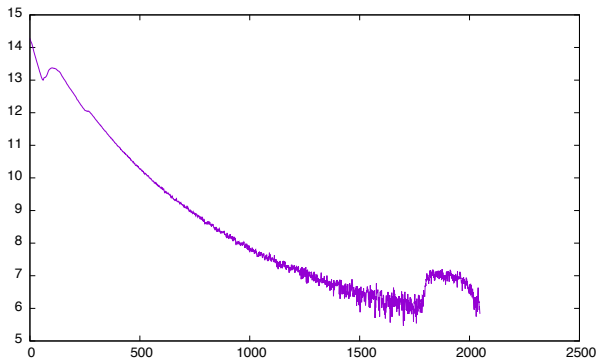
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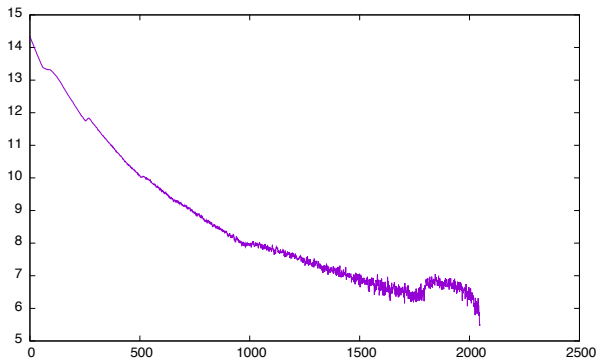
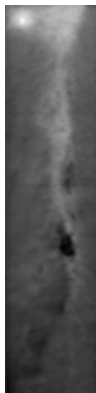


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## Methods:

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- future: compressed sensing, dictionary learning, tensor methods,...

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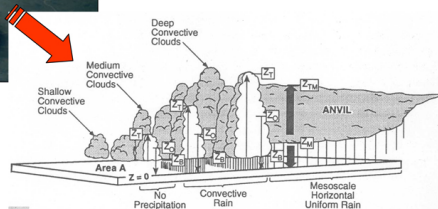
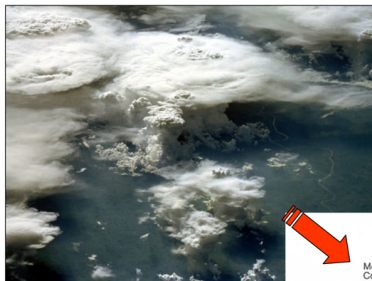
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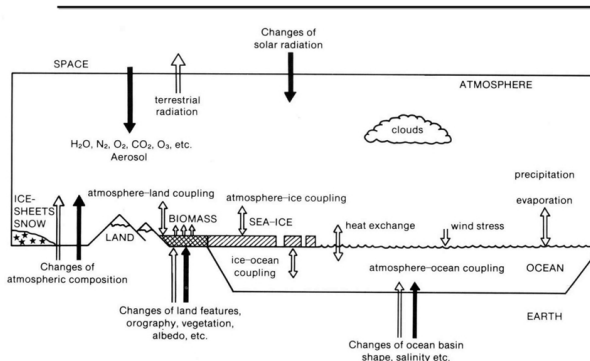


# NCAR National Center of Atmospheric Research CAM Community Atmospheric Model

Collaborators: P. Binev, R. DeVore, P. Lamby, (M. Fox-Rabinowitz, V. Krasnopolsky)



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**Figure 3.1:** Schematic illustration of the components of the coupled atmosphere-ocean-ice-land climatic system. The full arrows are examples of external processes, and the open arrows are examples of internal processes in climatic change (from Houghton, 1984).

# NCAR Model general Circulation Model

---

$$d\bar{\mathbf{V}}/dt + f\mathbf{k} \times \bar{\mathbf{V}} + \nabla\bar{\phi} = \mathbf{F}, \quad (\text{horizontal momentum})$$

$$d\bar{T}/dt - \kappa\bar{T}\omega/p = Q/c_p, \quad (\text{thermodynamic energy})$$

$$\nabla \cdot \bar{\mathbf{V}} + \partial\bar{\omega}/\partial p = 0, \quad (\text{mass continuity})$$

$$\partial\bar{\phi}/\partial p + R\bar{T}/p = 0, \quad (\text{hydrostatic equilibrium})$$

$$d\bar{q}/dt = S_q. \quad (\text{water vapor mass continuity})$$

Harmless looking terms  $\mathbf{F}$ ,  $Q$ , and  $S_q \Rightarrow$  “physics”

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General Circulation Model: fluid dynamics equation on the sphere

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**Bottleneck for numerical simulations:** modeling physics/chemistry

Long **W**ave **R**adiation: 70% – 90% of total cost



# Problem and Goal

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For LWR recovery  $\rightsquigarrow$

$$f : X \subset \mathbb{R}^{220} \rightarrow \mathbb{R}^{33}$$

from data  $\mathbf{z} = \{z^i = (x^i, y^i) : i = 1, \dots, N\} \subset X \times Y$ , where

$$N \sim 10^5$$

Inputs  $x \in X$  consist of 10 vertical profiles of local physical properties and gas concentrations plus a surface characteristic.

Outputs  $y$  consist of a vertical profile of **heating rates** and some radiation fluxes

outputs  $y = f(x)$  are computed via solving the physical model with input  $x$

# Key Issues

- Severe undersampling - Classical approximation schemes are not feasible
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- **Key question:** How much of the structure does an algorithm have to know in order to take advantage of it?



# Procedural Definition of Function Recovery

learn  $f$  from  $\mathbf{z} = \{(x^1, y^1), \dots, (x^N, y^N)\}$

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Candidates:

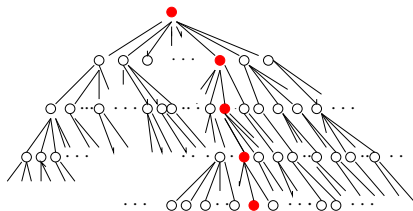
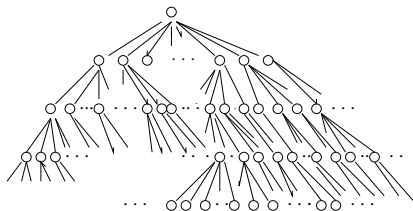
- kernel methods, artificial neural networks
- Recovery based on  $k$  nearest neighbor search
- Tree based schemes: random forests, sparse occupancy trees

# Sparse Occupancy Trees

Hierarchy of nested partitions of  $X$

$$X = \mathcal{P}_\emptyset \prec \mathcal{P}_0 \prec \mathcal{P}_1 \prec \dots,$$

$$X_{j,k} \in \mathcal{P}_j \rightsquigarrow X_{j,k} = \bigcup_{i \in \mathcal{I}_{j,k}} X_{j+1,i}$$

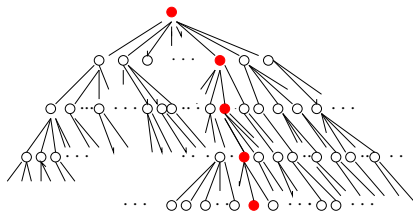
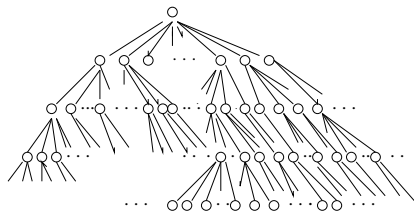


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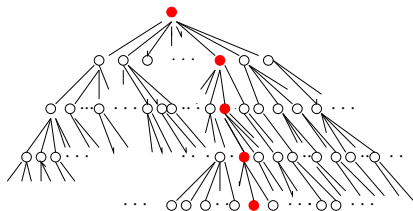
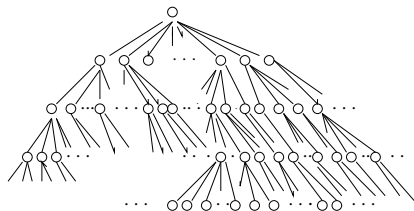
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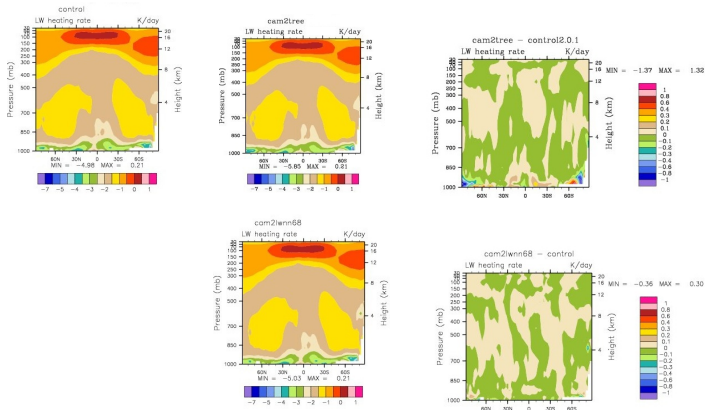


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- $O(LdN)$  operations to collect information about  $X$

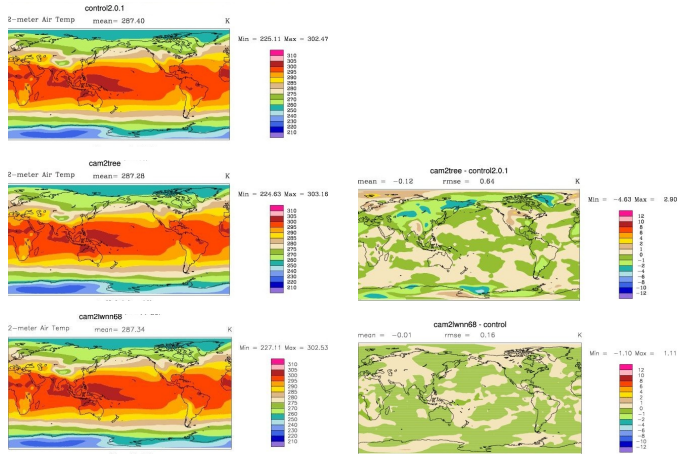


## Simulation Results



**Figure:** Comparison of the predicted annual zonal means of the LWR heating rates computed with the original parameterization (1 in 1. row), a tree based emulation (2, 3 in 1. row) and a neural network emulation (2. row). The right column plots the difference between the simulation and the control.

# Simulation Results



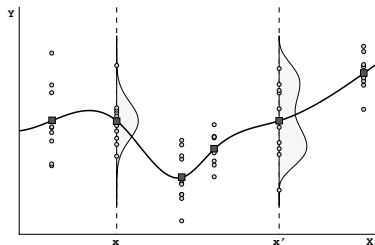
**Figure:** Comparison of the predicted annual means of the two meter air temperatures computed with the original parameterization (top row), a tree-based emulation (center row) and a neural network emulation (bottom row). The right column plots the difference between the simulation and the control.



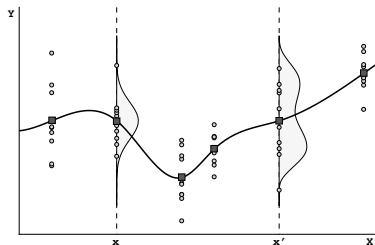
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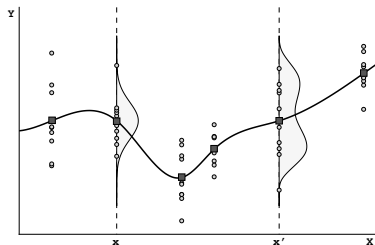
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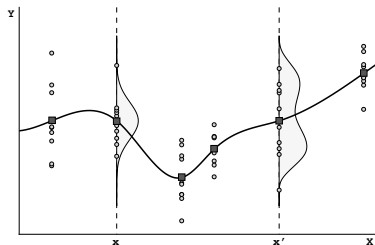
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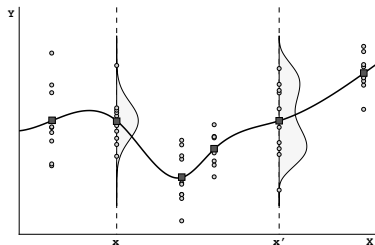
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$$\mathcal{E}(f) = \mathcal{E}(f_\rho) + \|f - f_\rho\|_{L_2(X, \rho_X)}^2, \quad \|\cdot\| := \|\cdot\|_{L_2(X, \rho_X)}$$

# Estimators

Key issue: proper balance of bias and variance

- Adaptive Tree Partitioning
- Greedy algorithms

⇒ **universality**, i.e., realization of best rates without a priori knowledge about the searched regression function

# A Performance Theorem

Bench mark:  $f \in L_2(X, \rho_X) \rightsquigarrow \mathcal{T}(f, \eta)$  via  $L_2(X, \rho_X)$ - projections

$$|f|_{\mathcal{B}^s}^p := \sup_{\eta > 0} \eta^p \#(\mathcal{T}(f, \eta)), \quad \text{where } p := (s + 1/2)^{-1} \rightsquigarrow$$



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$$\mathbb{E}(\|f_\rho - \hat{f}_{\mathbf{z}}\|^2) \leq C \left( \frac{d \log N}{N} \right)^{\frac{2s}{2s+1}}$$

Moreover, the scheme is **universally consistent** and need **not** know  $s$ .

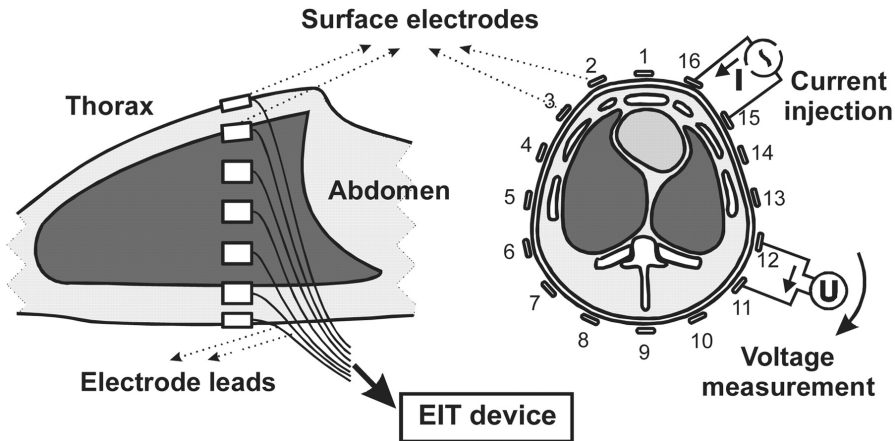
# Comments

- the convergence rates are best possible for a given “regularity” order  $s > 0$ ;
- the smaller  $s$  the weaker the hypothesis,  $\mathcal{B}^0 = L_2(X, \rho_X)$ ;
- to achieve this rate the algorithm does **not** need to know the property  $f_\rho \in \mathcal{B}^s$  but automatically exploits such a property (adaptivity  $\rightsquigarrow$  universality);
- for **arbitrary** densities  $\rho$  and piecewise polynomial estimators the estimates in probability hold only for piecewise constants, higher orders require restrictions on  $\rho$ , the rate in expectation holds for higher order piecewise polynomial estimators;
- analogous results are valid for **tree based adaptive classifiers**

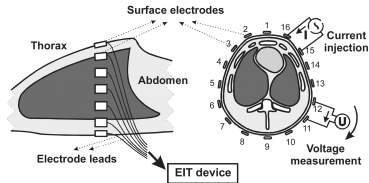
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# Example: Electron Impedance Tomography: “many parameters...”



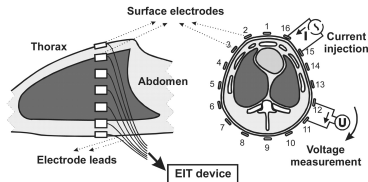
# Example: EIT: Model



$a(\omega, \mathbf{x}) : \Omega \times D \rightarrow \mathbb{R}$  (unknown) random conductivity field



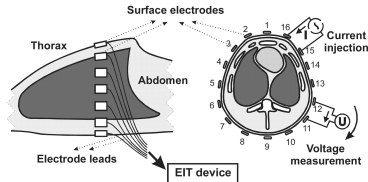
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**Forward problem:** given  $\mathbf{I} = (I_1, \dots, I_M) \in \mathbb{R}_0^M$ , find  $(u, \mathbf{U}) \in L^2_\rho(\Omega; X)$ ,  
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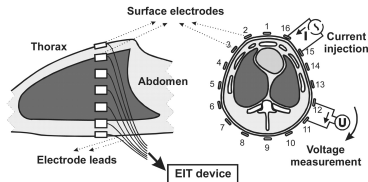
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**Inverse problem:** find  $a(\omega, x) = a_0(x) + \sum_{j \in \mathbb{N}} y_j \psi_j(x) = a(y, x)$

# Solution Manifold...

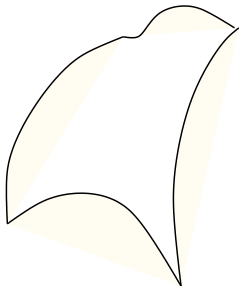
Find  $u \in \mathcal{H}$ , s.t.

$$F(u, \mathbf{y}) = 0, \quad \mathbf{y} \in \mathcal{Y} \quad \rightsquigarrow \mathcal{M} := \{u(\mathbf{y}) \in \mathcal{H} : F(u(\mathbf{y}), \mathbf{y}) = 0\}$$

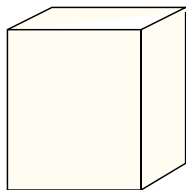
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solution manifold  $\mathcal{M}$

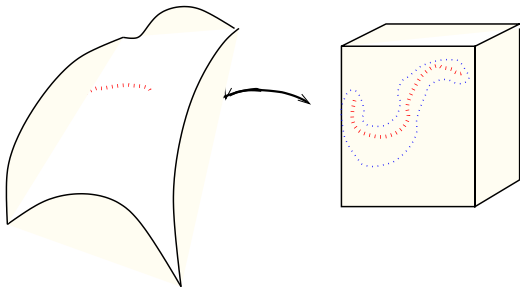


parameter domain  $\mathcal{Y}$

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data:  $\mathbf{d} = \ell(u(\mathbf{y}^*)) \in \mathbb{R}^d$

find the parameters  $\mathbf{y}^* \in \mathcal{Y}$

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