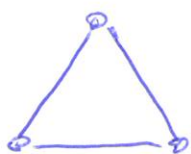


FBDA, 23.11.2018

4.2. Multidimensional Scaling

Problem 1) $\delta_{ij} = 1$ if $i \neq j$ $\delta_{ij} = 0$ if $i = j$ $(i, j \in \{1, 2, 3\})$

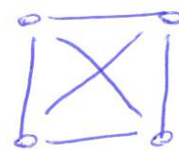
$$\Delta_1 = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix} \quad \delta_{ij}$$



$$\Delta_2 = \begin{pmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 1 & 1 & 1 & 0 \end{pmatrix}$$



$$\Delta_3 = \begin{pmatrix} 0 & 1 & \sqrt{2} & 1 \\ 1 & 0 & 1 & \sqrt{2} \\ \sqrt{2} & 1 & 0 & 1 \\ 1 & \sqrt{2} & 1 & 0 \end{pmatrix}$$



Given n Objects O_1, O_2, \dots, O_n and

pairwise dissimilarities δ_{ij} between objects i and

j . We assume $\delta_{ij} = \delta_{ji}$ and $\delta_{ii} = 0$.

and $\delta_{ij} \geq 0$ for all $i, j = 1, \dots, n$.

Define $\Delta = (\delta_{ij})_{1 \leq i, j \leq n}$ as the dissimilarity matrix

$$\text{and } U_n = \left\{ \Delta = (\delta_{ij})_{1 \leq i, j \leq n} \mid \begin{array}{l} \delta_{ij} = \delta_{ji} \geq 0 \\ \delta_{ii} = 0 \text{ for all } i, j \end{array} \right\}$$

the set of all dissimilarity matrices.

Objective. Find n points x_1, \dots, x_n in a

Euclidean space, typically \mathbb{R}^k , such that the

distances $\|x_i - x_j\|$ fit the dissimilarity δ_{ij} .

Example: Towns, δ_{ij} is the driving time from town i to town j . \rightarrow Find an embedding in \mathbb{R} .

Notation $X = [x_1 \dots x_n]^T \in \mathbb{R}^{n \times k}$

$$d_{ij}(X) = \|x_i - x_j\| \quad D(X) = (d_{ij}(X))_{1 \leq i, j \leq n}$$

$$\Delta^{(q)} = (\delta_{ij}^{(q)})_{ij} \quad \text{and} \quad D^{(q)}(X) = (d_{ij}^{(q)}(X))_{ij}$$

Optimization Problem: given q

$$\min_{X \in \mathbb{R}^{n \times k}} \| \Delta^{(q)} - D^{(q)}(X) \|$$

4.2.4. Characterizing Euclidean Distance Matrices

$\Delta = (\delta_{ij})_{i,j} \in \mathcal{V}_n$ is called Euclidean matrix
(or it has a Euclidean embedding in \mathbb{R}^k)

if there are $x_1, \dots, x_n \in \mathbb{R}^k$ such that

$$\delta_{ij} = \|x_i - x_j\| \quad \forall i, j$$

where $\|y\| = \sqrt{\sum_{i=1}^k y_i^2}$.

$$E_n = I_n - \frac{1}{n} \mathbf{1}_n \mathbf{1}_n^T$$

Thm 4.3. $\Delta \in \mathcal{V}_n$ has a Euclidean Embedding
in \mathbb{R}^k if and only if $-\frac{1}{2} E_n \Delta^{(2)} E_n$ is nonnegative
definite. and $\text{rk}(E_n \Delta^{(2)} E_n) \leq k$.

The least k which allows for an embedding
is called dimensionality of Δ .

Proof. $X = (x_1, \dots, x_n)^T \in \mathbb{R}^{n \times k}$

$$\Delta = \mathcal{D}(X) \quad \Delta^{(q)} = \mathcal{D}^{(q)}(X) \quad q=2.$$

$$\|x_i - x_j\|^2 = \|x_i\|^2 + \|x_j\|^2 - 2x_i^T x_j$$

$$x_i^T x_j = \frac{1}{2} (\|x_i\|^2 + \|x_j\|^2 - \|x_i - x_j\|^2)$$

$$-\frac{1}{2} \|x_i - x_j\|^2 = -\frac{1}{2} \|x_i\|^2 - \frac{1}{2} \|x_j\|^2 + x_i^T x_j$$

generalize $\rightarrow -\frac{1}{2} D^{(2)}(X) = XX^T - \mathbf{1} \hat{\lambda}^T - \hat{\lambda} \mathbf{1}^T$

$$\hat{\lambda} = (x_1^T x_1, x_2^T x_2, \dots, x_n^T x_n)^T$$

$$\Rightarrow -\frac{1}{2} E_n D^{(2)}(X) E_n = E_n X X^T E_n = \left. \begin{array}{l} -E_n \hat{\lambda}^T E_n \\ -E_n \hat{\lambda} \mathbf{1}^T E_n \end{array} \right\} \text{they are zero}$$

$$(E_n \mathbf{1} = 0)$$

$$\Rightarrow -\frac{1}{2} E_n D^{(2)}(X) E_n = E_n X X^T E_n \quad (*)$$

$$E_n = E_n^T = (E_n X) (E_n X)^T \succeq 0 \quad \text{n.n.d.}$$

the reverse direction:

$$-\frac{1}{2} E_n D^{(2)} E_n \succeq 0$$

$$-\frac{1}{2} E_n D^{(2)} E_n = V^T \Lambda V = X X^T \quad X \in \mathbb{R}^{n \times k}$$

exercise

$$\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n) \Rightarrow \Lambda = \Lambda^{1/2} \Lambda^{1/2}$$

$\lambda_i \geq 0$

$$\text{diag}(\sqrt{\lambda_1}, \sqrt{\lambda_2}, \dots)$$

$$\text{rk}\left(\frac{1}{2} E_n D^{(2)} E_n\right) = K \quad \lambda_{K+1}, \lambda_{K+2}, \dots, \lambda_n = 0$$

$$X \in \mathbb{R}^{n \times K} : \frac{1}{2} E_n D^{(2)} E_n = X X^T$$

$$X X^T = \frac{1}{2} E_n D^{(2)} E_n$$

$$X^T E_n = X^T$$

$$X = \frac{1}{2} E_n D^{(2)} E_n = V^T \Lambda V$$

hint $\rightarrow X = V^T \Lambda^{1/2}$ v_i eigenvectors

$$\left(\frac{1}{2} E_n D^{(2)} E_n\right) v_i = \lambda_i v_i \Rightarrow v_i \in \text{Im}(E_n)$$

$$\Rightarrow E_n v_i = v_i \Rightarrow X^T E_n = X^T$$

$$\frac{1}{2} E_n D^{(2)}(X) E_n = E_n X X^T E_n = X X^T = \frac{1}{2} E_n D^{(2)} E_n$$

$$\Rightarrow D^{(2)}(X) = \Delta$$

(exercise) \rightarrow hollow matrices. \square

$-\frac{1}{2} E_n \Delta^{(2)} E_n$ in general is not non-negative definite. $\exists \lambda_i \lambda_i < 0$

Thm. 4.4. Given $\Delta \in V_n$,

$$-\frac{1}{2} E_n \Delta^{(2)} E_n = V \text{diag}(\lambda_1, \dots, \lambda_n) V^T \quad \text{spectral decomp.}$$

with $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n$

$V = [v_1, \dots, v_n]$ corr. eigenvectors

$$\min_{X \in \mathbb{R}^{n \times k}} \|E_n (\Delta^{(2)} - D(X)) E_n\|$$

has a solution $X^* = (\sqrt{\lambda_1^+} v_1, \sqrt{\lambda_2^+} v_2, \dots, \sqrt{\lambda_k^+} v_k)$

$$\lambda^+ = \max\{\lambda, 0\}$$

Proof: $\min_{\substack{A \succeq 0 \\ \text{rk}(A) \leq k}} \left\| -\frac{1}{2} E_n \Delta^{(2)} E_n - A \right\|^2 \quad (*)$

reminder:

$$-\frac{1}{2} E_n D^{(2)}(X) E_n = E_n X X^T E_n \succeq 0 \quad \text{rk}\left(-\frac{1}{2} E_n D^{(2)}(X) E_n\right) \leq k$$

(Thm 2.0) : the min of (*) is attained at

$$A^* = V \text{diag}(\lambda_1^+, \lambda_2^+, \dots, \lambda_k^+, 0, \dots, 0) V^T$$

$$X^* = (\sqrt{\lambda_1^+} v_1, \sqrt{\lambda_2^+} v_2, \dots, \sqrt{\lambda_k^+} v_k) \in \mathbb{R}^{n \times k}$$

$$\Rightarrow A^* = X^* X^{*T}$$

(exercise)

□

4. 2-3. Non-linear dimensionality Reduction

→ Manifold learning

geodesics

ISOMAP (2000) - Science

Given data $x_1, \dots, x_n \in \mathbb{R}^p$ (lying on a manifold)
 e.g., the swiss roll.

→ First we construct a graph.

1) vertices v_i for each x_i

2) Connect v_i and v_j if $\|x_i - x_j\| < \epsilon$

(or another: connect to K -nearest neighbours)

3) For each pair, compute the shortest path between v_i, v_j : $d(v_i, v_j)$ (Dijkstra's alg.)

4) Apply MDS on the basis of geodesic distances $\Delta = (d(v_i, v_j))_{1 \leq i, j \leq n}$.

Shortcomings of this approach:

- Choosing ϵ : difficult, ^{not} robust to noise perturbation

- Computational complexity: Dykstein's alg.

MDS

- Very large distances may distort local neighborhoods